
Corrigendum: Broad learning system-based fixed-time control for a robot with input saturation and output constraint

It has come to the attention of the publisher that the article, Zhang, D., Sun, W., Han, X., Yu, X. and Han, Z. (2025), “Broad learning system-based fixed-time control for a robot with input saturation and output constraint”, *Robotic*

Intelligence and Automation, Vol. 46 No. 1, pp.13–29. <https://doi.org/10.1108/RIA-09-2024-0206>, omitted part of the funding information.

The missing funding information is as follows:

The Fundamental Research Funds for the Beijing Municipal Universities (bistu71E2510905).

The National Natural Science Foundation of China under Grant (62503058).

Additionally, the grant number “6242781” for the National Natural Science Foundation of China was published incorrectly; the correct grant number is “62427813”.

The publisher asks that funding information be entered correctly at submission and confirmed at article proofing stage.

The current issue and full text archive of this journal is available on Emerald Insight at: <https://www.emerald.com/insight/2754-6969.htm>



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